

Stochastic super-resolution for Gaussian textures

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Outline

A gentle introduction to images and textures

Introduction to stochastic super-resolution

The Gaussian SR method

Comparison of Gaussian SR with other methods

Fails of the method

A little lie

Conclusion

A gentle introduction to images and textures

What is an image ?



$\in \mathbb{R}^{M \times N}$

Grayscale image

What is a RGB image ?

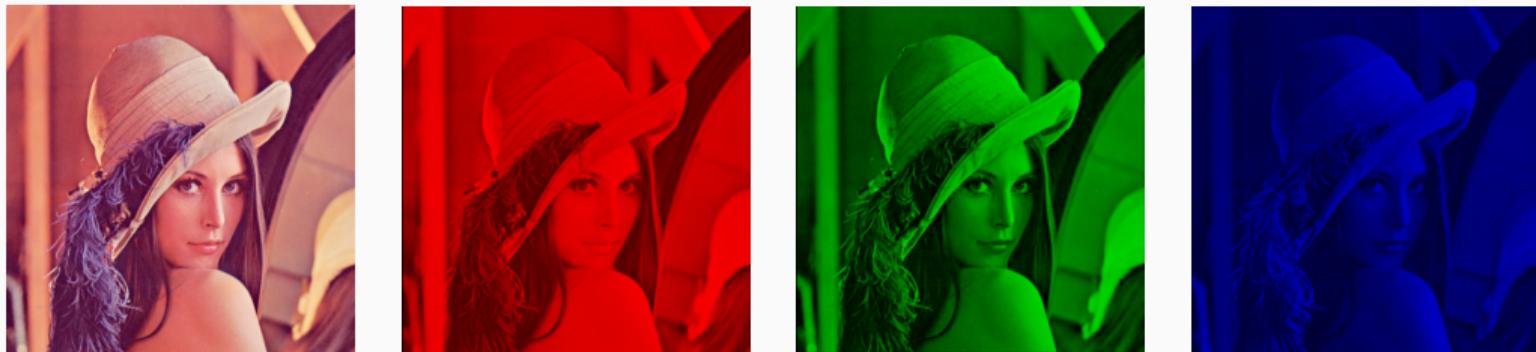


image =
 $\in \mathbb{R}^{3 \times M \times N}$

R
 $\in \mathbb{R}^{1 \times M \times N}$

G
 $\in \mathbb{R}^{1 \times M \times N}$

B
 $\in \mathbb{R}^{1 \times M \times N}$

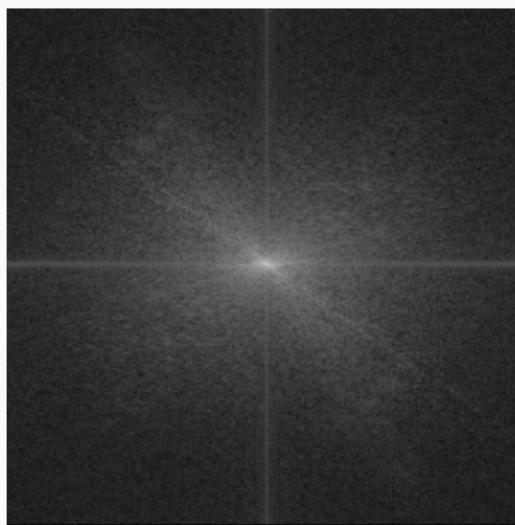
Discrete Fourier transform

Let $\mathbf{X} \in \mathbb{R}^{M \times N}$ be an image. For $\xi = (\xi_1, \xi_2) \in [0, M - 1] \times [0, N - 1]$, we consider:

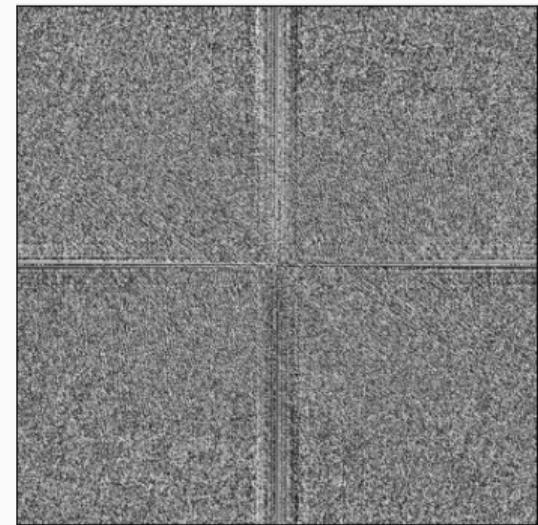
$$\hat{\mathbf{X}}(\xi) = \sum_{(k,\ell) \in [0, M-1] \times [0, N-1]^2} \mathbf{X}(k, \ell) e^{-\frac{2ik\xi_1\pi}{M}} e^{-\frac{2i\ell\xi_2\pi}{N}}$$



image



Modulus



Phase

Discrete Fourier transform - Properties

Let $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^{M \times N}$ be two images,

- FFT:

$\hat{\mathbf{X}}$ can be computed in $\mathcal{O}(MN \log(MN))$ with the Fast Fourier Transform algorithm.

- Convolution:

For $x \in [0, M - 1] \times [0, N - 1]$, if $(\mathbf{X} \star \mathbf{Y})(x) = \sum_{y \in [0, n-1]^2} \mathbf{X}(x - y) \mathbf{Y}(y)$,

$$\widehat{\mathbf{X} \star \mathbf{Y}} = \hat{\mathbf{X}} \odot \hat{\mathbf{Y}}$$

Introduction to microtextures



Micro-texture



Macro-texture



Some pebbles

Images extracted from Bruno Galerne's slides

Introduction to stochastic super-resolution

The super-resolution

LR image (62×47 pixels)



Image extracted from dark sources

The number of pixels has been divided by $r = 32$.

The super-resolution

LR image (62×47 pixels)

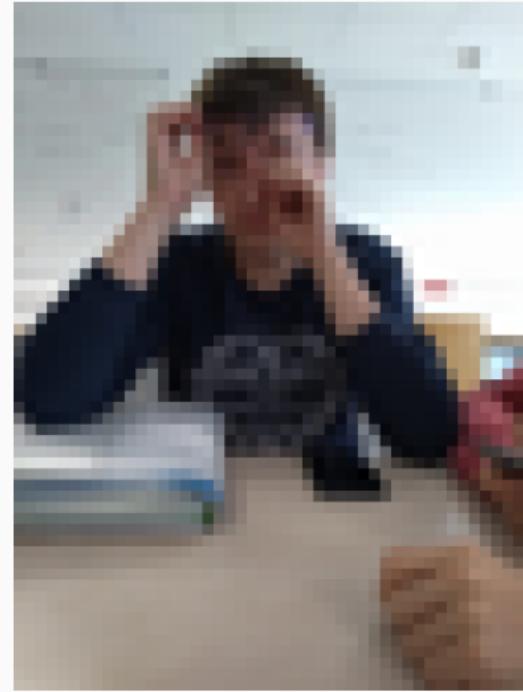


Image extracted from dark sources

The number of pixels has been divided by $r = 32$.

The super-resolution

HR image (1984×1504 pixels)



LR image (62×47 pixels)

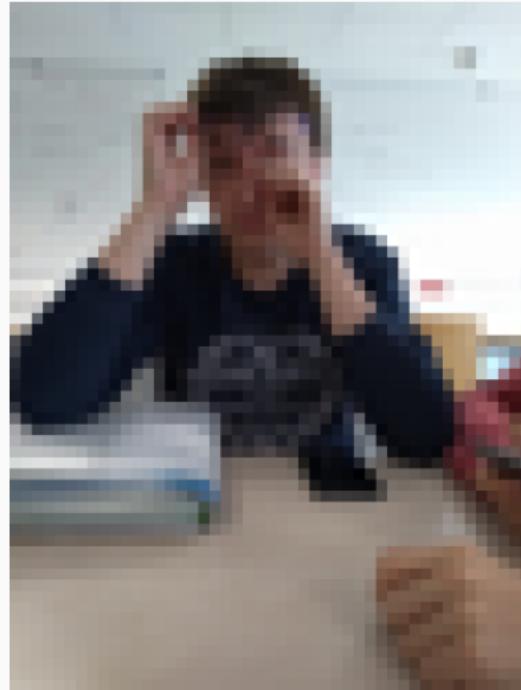
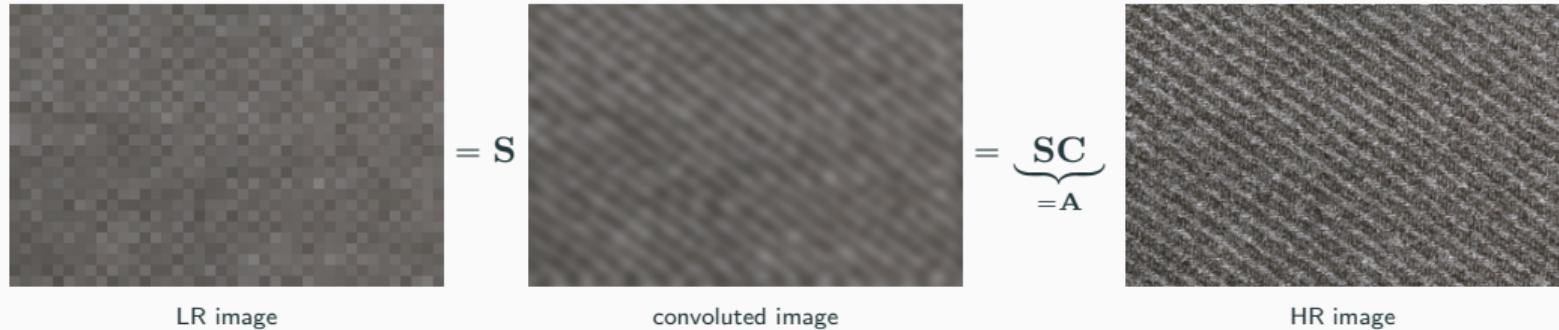


Image extracted from dark sources

The number of pixels has been divided by $r = 32$.

The Single Image Super-Resolution (SISR)



- SISR setting litterature: [Bruna et al., 2016]¹ [Ledig et al., 2017]², [Wang et al., 2019]³, [Johnson et al., 2016]⁴, [Hertrich, Houdard, et al., 2022]⁵, [Hertrich, Nguyen, et al., 2022]⁶, [Chatillon et al., 2022]⁷

¹Bruna, J., Sprechmann, P., & LeCun, Y. (2016). Super-Resolution with Deep Convolutional Sufficient Statistics. *ICLR 2016*

²Ledig, C., Theis, L., & Huszár, F. e. a. (2017). Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network. *CVPR 2017*

³Wang, X., Yu, K., Wu, S., Gu, J., Liu, Y., Dong, C., Qiao, Y., & Loy, C. C. (2019). ESRGAN: Enhanced Super-Resolution Generative Adversarial Networks. *ECCV 2018*

⁴Johnson, J., Alahi, A., & Fei-Fei, L. (2016). Perceptual losses for real-time style transfer and super-resolution. *ECCV 2016*

⁵Hertrich, J., Houdard, A., & Redenbach, C. (2022). Wasserstein Patch Prior for Image Superresolution. *IEEE Transactions on Computational Imaging*

⁶Hertrich, J., Nguyen, L. D. P., Aujol, J.-F., Bernard, D., Berthoumieu, Y., Saadaldin, A., & Steidl, G. (2022). PCA Reduced Gaussian Mixture Models with Applications in Superresolution. *Inverse Problems and Imaging*

⁷Chatillon, P., Gousseau, Y., & Lefebvre, S. (2022). A statistically constrained internal method for single image super-resolution. *ICPR 2022*

The stochastic super-resolution

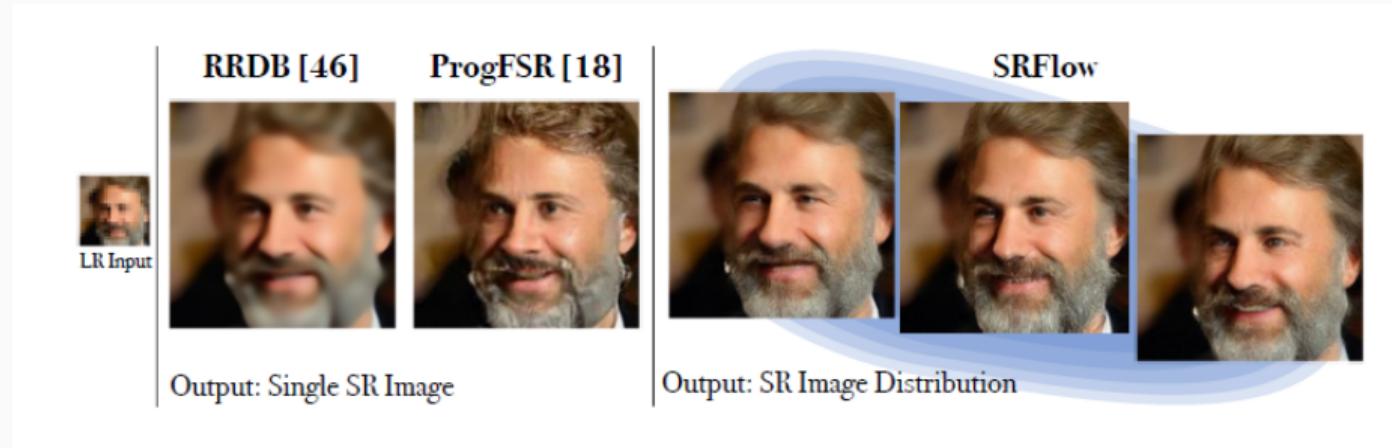


Image extracted from [Lugmayr et al., 2020]

Stochastic super-resolution litterature: SRFlow [Lugmayr et al., 2020]⁸, SR3 [Saharia et al., 2022]⁹, CEM [Bahat and Michaeli, 2020]¹⁰.

⁸Lugmayr, A., Danelljan, M., Van Gool, L., & Timofte, R. (2020). SRFlow: Learning the Super-Resolution Space with Normalizing Flow. *ECCV 2020*

⁹Saharia, C., Ho, J., Chan, W., Salimans, T., Fleet, D. J., & Norouzi, M. (2022). Image Super-Resolution Via Iterative Refinement. *IEEE Transactions on Pattern Analysis and Machine Intelligence*

¹⁰Bahat, Y., & Michaeli, T. (2020). Explorable super resolution. *CVPR*

Stochastic super-resolution: an example

HR image



LR image (by a factor $r = 16$)

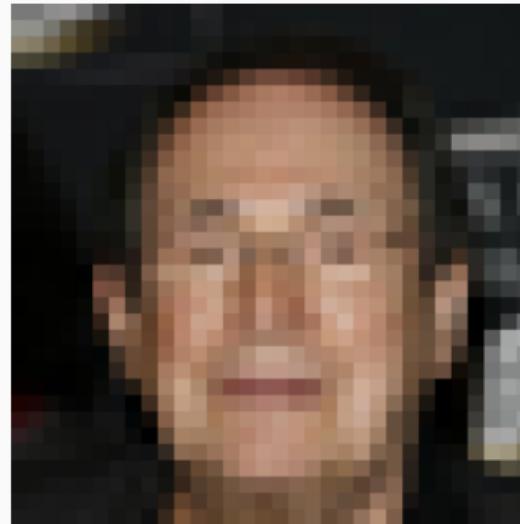


Image of Robert Hossein extracted from the dataset CelebA.

Stochastic super-resolution: an example



Image of Robert Hossein extracted from the dataset CelebA.

All these images have the same LR version !

Stochastic super-resolution: an example



Image of Robert Hossein extracted from the dataset CelebA.

Stochastic super-resolution for textures



Image extracted from [Galerne et al., 2011a]¹¹

¹¹Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1. https://doi.org/10.5201/ipol.2011.ggrm_rpn

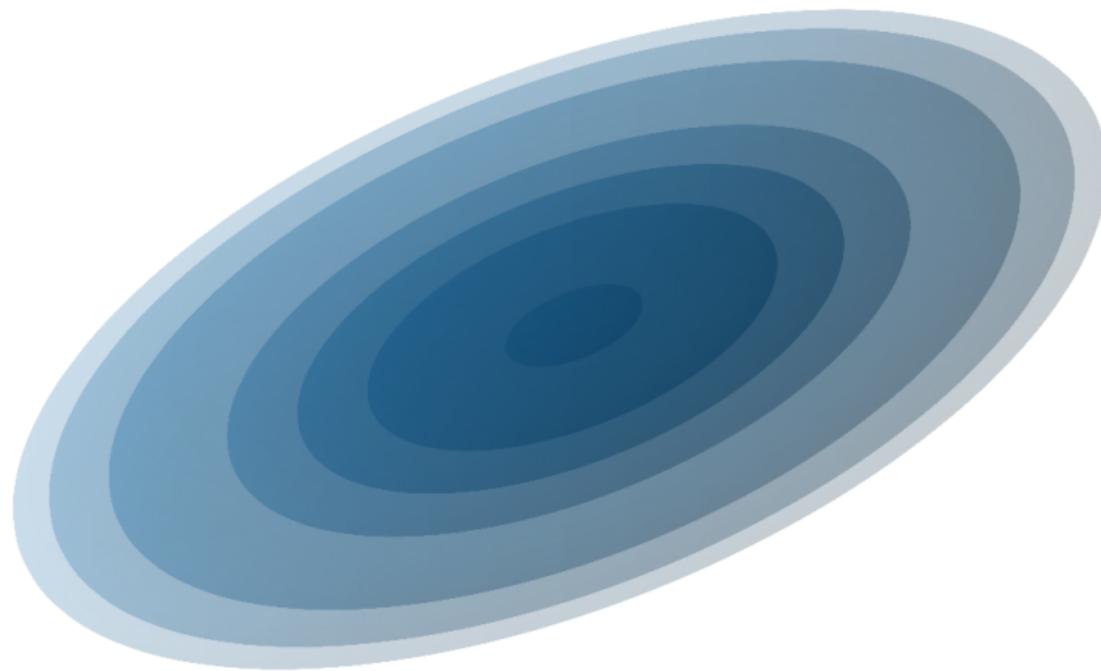
Stochastic super-resolution for textures



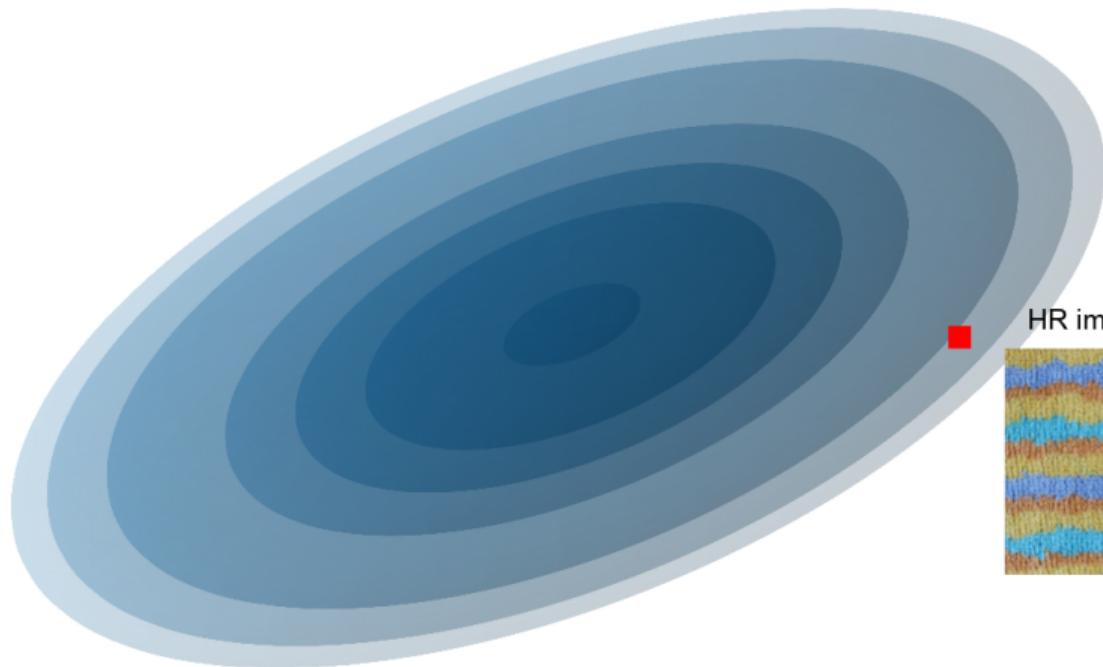
Image extracted from Courcimont website

The Gaussian SR method

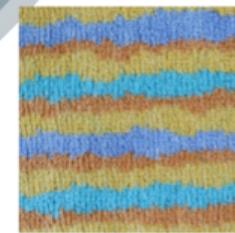
ADSN(U)



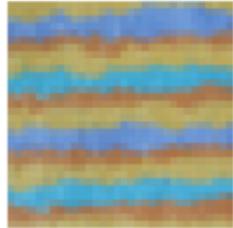
ADSN(U)



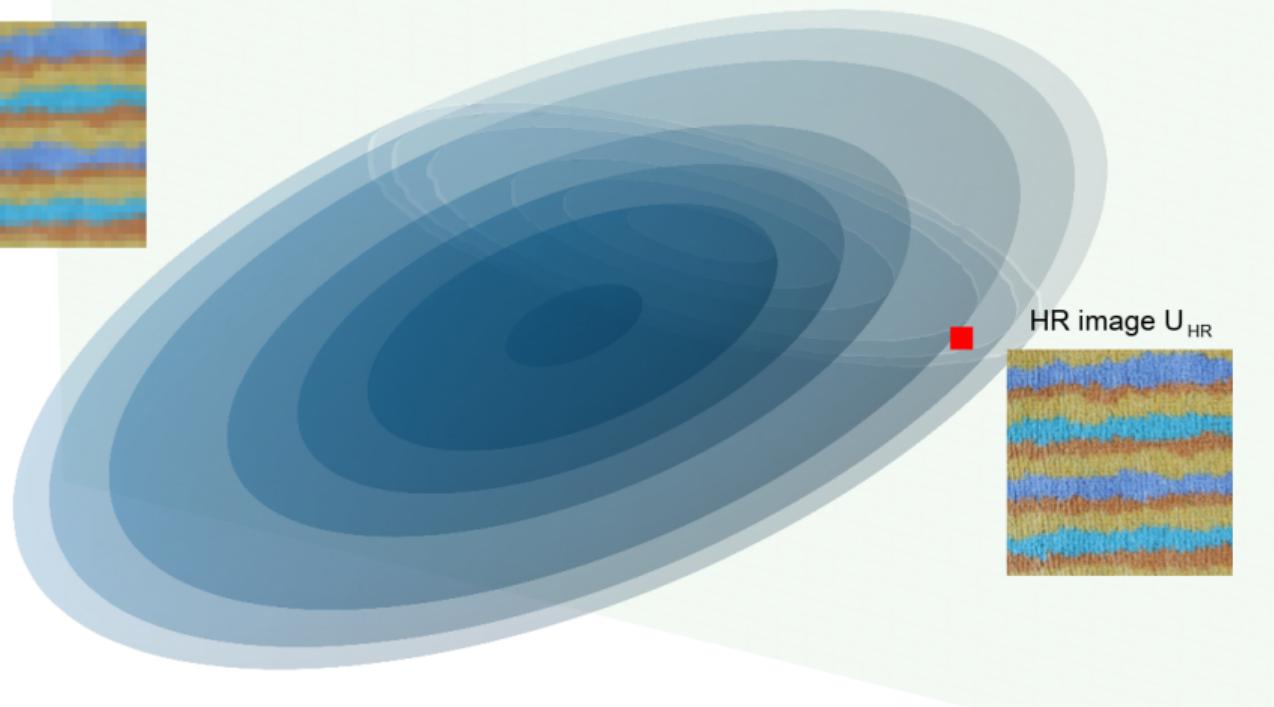
HR image U_{HR}



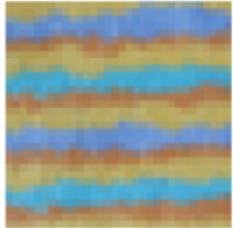
$$AU = U_{LR}$$



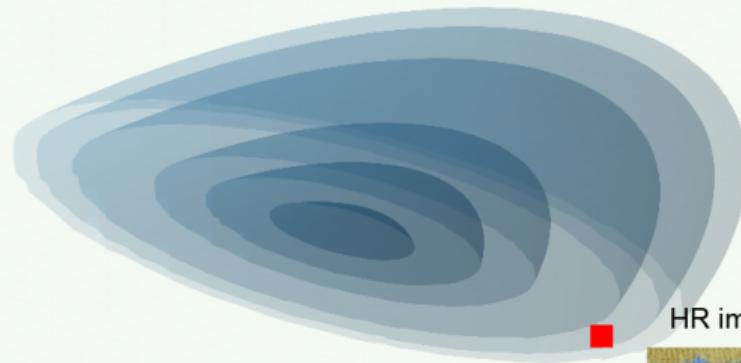
ADSN(U)



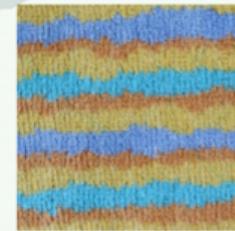
$$AU = U_{LR}$$



ADSN(U)



HR image U_{HR}



The Asymptotic Discrete Spot Noise (ADSN) model [Galerne et al., 2011b]¹³

Let $\mathbf{U} \in \mathbb{R}^{\Omega_{M,N}}$ be a grayscale image, m its grayscale mean and $\mathbf{t} = \frac{1}{\sqrt{MN}}(\mathbf{U} - m)$ its associated texton. Let \mathbf{W} be a white Gaussian noise,

$$\mathbf{X} = \mathbf{t} \star \mathbf{W} \sim \text{ADSN}(\mathbf{U}) = \mathcal{N}(\mathbf{0}, \Gamma) \quad \text{which is a stationary law}$$

Γ represents the convolution by the kernel $\gamma = \mathbf{t} \star \check{\mathbf{t}}$: Γ can be stored.

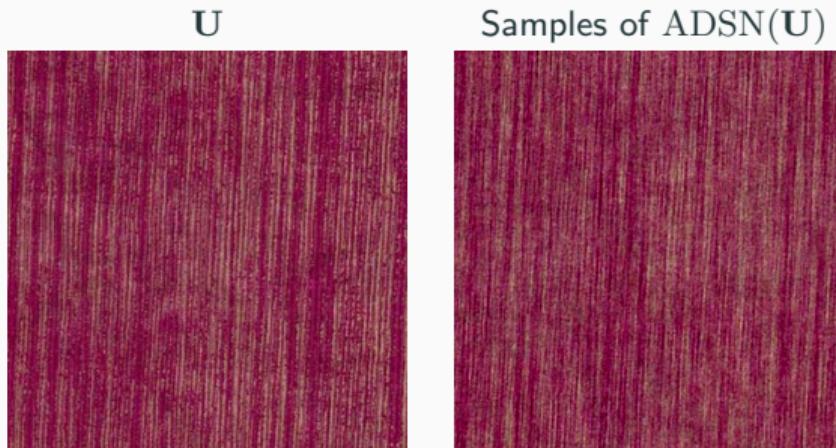


Image extracted from [Galerne et al., 2011a]¹²

¹²Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1. https://doi.org/10.5201/ipol.2011.ggm_rpn

¹³Galerne, B., Gousseau, Y., & Morel, J.-M. (2011b). Random Phase Textures: Theory and Synthesis. *IEEE Transactions on Image Processing*

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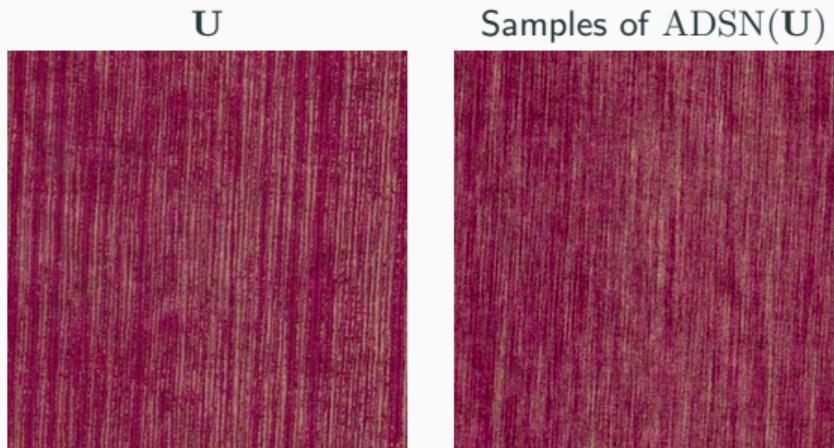


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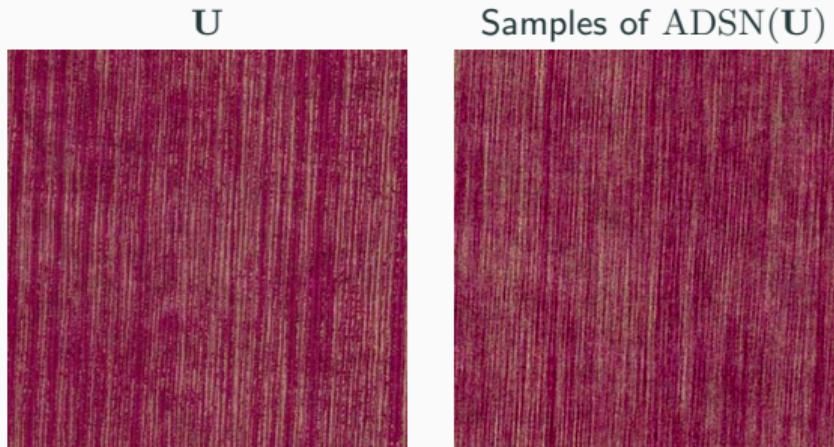


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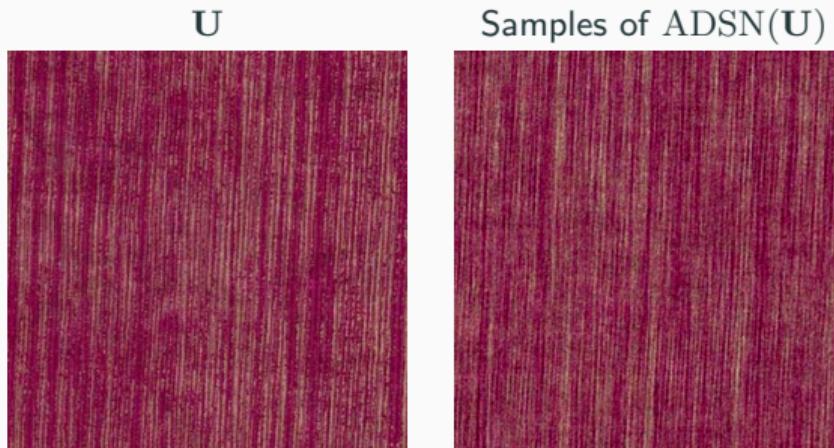


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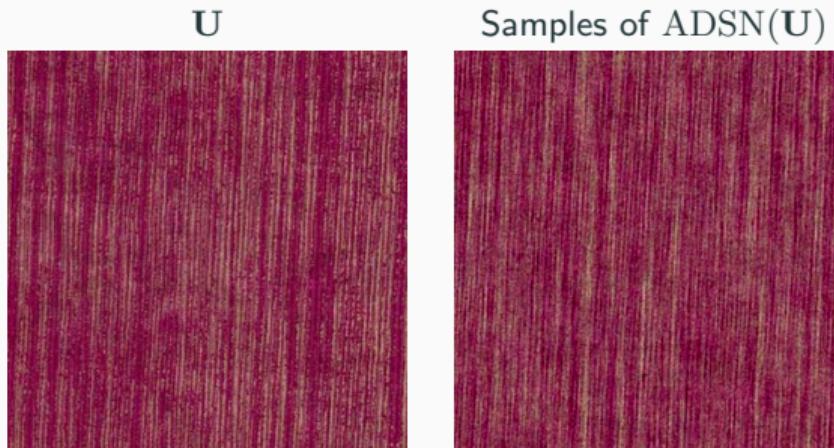


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The conditional Gaussian simulation

Following ideas from [Galerne and Leclaire, 2017]¹⁴ Let \mathbf{X} be a **Gaussian** vector, and \mathbf{A} be a linear operator, $\mathbb{E}(\mathbf{X}|\mathbf{AX})$ and $\mathbf{X} - \mathbb{E}(\mathbf{X}|\mathbf{AX})$ are independent. Consequently, if $\tilde{\mathbf{X}}$ is independent of \mathbf{X} with the same distribution, then:

$$\mathbb{E}(\mathbf{X}|\mathbf{AX}) + [\tilde{\mathbf{X}} - \mathbb{E}(\tilde{\mathbf{X}}|\mathbf{A}\tilde{\mathbf{X}})] \sim \mathbf{X}|\mathbf{AX}$$

¹⁴Galerne, B., & Leclaire, A. (2017). Texture Inpainting Using Efficient Gaussian Conditional Simulation. *SIAM Journal on Imaging Sciences*, 10(3), 1483–1510. <https://doi.org/10.1137/16M108700X>

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$$\mathbb{E}(\mathbf{X}|\mathbf{AX}) + [\tilde{\mathbf{X}} - \mathbb{E}(\tilde{\mathbf{X}}|\mathbf{A}\tilde{\mathbf{X}})] \sim \mathbf{X}|\mathbf{AX}$$

Furthermore, if \mathbf{X} is zero-mean, there exists $\boldsymbol{\Lambda} \in \mathbb{R}^{\Omega_{M/r,N/r} \times \Omega_{M,N}}$ such that $\mathbb{E}(\mathbf{X}|\mathbf{AX}) = \boldsymbol{\Lambda}^T \mathbf{AX}$ and:

$$\mathbb{E}(\mathbf{X}|\mathbf{AX}) = \boldsymbol{\Lambda}^T \mathbf{AX} \iff \mathbf{A}\boldsymbol{\Gamma}\boldsymbol{\Lambda}^T \boldsymbol{\Lambda} = \mathbf{A}\boldsymbol{\Gamma}.$$

¹⁴Galerne, B., & Leclaire, A. (2017). Texture Inpainting Using Efficient Gaussian Conditional Simulation. *SIAM Journal on Imaging Sciences*, 10(3), 1583–1612. <https://doi.org/10.1137/16M108700X>

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$$\mathbb{E}(\mathbf{X}|\mathbf{AX}) + [\tilde{\mathbf{X}} - \mathbb{E}(\tilde{\mathbf{X}}|\mathbf{A}\tilde{\mathbf{X}})] \sim \mathbf{X}|\mathbf{AX}$$

Furthermore, if \mathbf{X} is zero-mean, there exists $\Lambda \in \mathbb{R}^{\Omega_{M/r,N/r} \times \Omega_{M,N}}$ such that $\mathbb{E}(\mathbf{X}|\mathbf{AX}) = \Lambda^T \mathbf{AX}$ and:

$$\mathbb{E}(\mathbf{X}|\mathbf{AX}) = \Lambda^T \mathbf{AX} \iff \mathbf{A}\Gamma\mathbf{A}^T \Lambda = \mathbf{A}\Gamma.$$

Consequence: To sample $\mathbf{X}_{\text{SR}} \sim \text{ADSN}(\mathbf{U}) = \mathcal{N}(\mathbf{0}, \boldsymbol{\Gamma})$, conditioned on $\mathbf{AX}_{\text{SR}} = \mathbf{U}_{\text{LR}}$, we aim:

$$\Lambda^T \mathbf{U}_{\text{LR}} + (\tilde{\mathbf{X}} - \Lambda^T \mathbf{AX}) \quad \text{with } \tilde{\mathbf{X}} \sim \text{ADSN}(\mathbf{U}) = \mathcal{N}(\mathbf{0}, \boldsymbol{\Gamma})$$

¹⁴Galerne, B., & Leclaire, A. (2017). Texture Inpainting Using Efficient Gaussian Conditional Simulation. *SIAM Journal on Imaging Sciences*

The Gaussian SR method

For a given input image $\mathbf{U}_{\text{HR}} \in \mathbb{R}^{\Omega_{M,N}}$, its associated ADSN model $\text{ADSN}(\mathbf{U})$ and its LR version $\mathbf{U}_{\text{LR}} = \mathbf{A}\mathbf{U}_{\text{HR}}$, we would like to sample $\mathbf{X}_{\text{SR}} \sim \text{ADSN}(\mathbf{U})$ conditioned on $\mathbf{A}\mathbf{X}_{\text{SR}} = \mathbf{U}_{\text{LR}}$, that is:

$$\mathbf{X}_{\text{SR}} = \boldsymbol{\Lambda}^T \mathbf{U}_{\text{LR}} + (\tilde{\mathbf{X}} - \boldsymbol{\Lambda}^T \mathbf{A}\tilde{\mathbf{X}}) \quad \text{with } \tilde{\mathbf{X}} \sim \text{ADSN}(\mathbf{U}) = \mathcal{N}(\mathbf{0}, \boldsymbol{\Gamma}), \text{ independent of } \mathbf{U}_{\text{HR}}$$

With $\boldsymbol{\Lambda}$ verifying the kriging equation:

$$\mathbf{A}\boldsymbol{\Gamma}\mathbf{A}^T \boldsymbol{\Lambda} = \mathbf{A}\boldsymbol{\Gamma}. \quad (1)$$



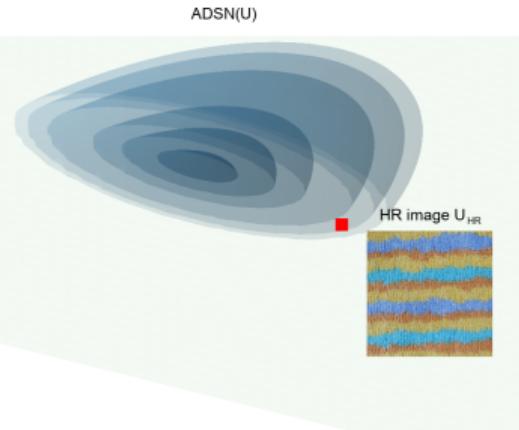
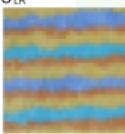
SR image: \mathbf{X}_{SR}

Kriging component: $\boldsymbol{\Lambda}^T \mathbf{U}_{\text{LR}}$

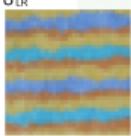
Innovation component: $\tilde{\mathbf{X}} - \boldsymbol{\Lambda}^T \mathbf{A}\tilde{\mathbf{X}}$

Image extracted from [Galerne et al., 2011a]

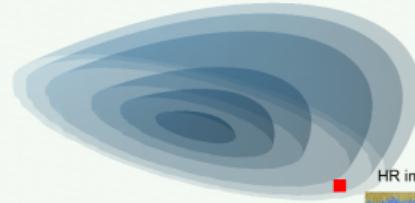
$$AU =$$



$$AU =$$



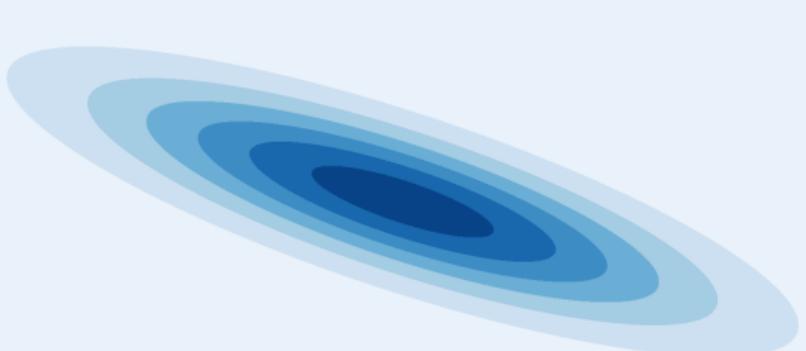
ADSN(U)



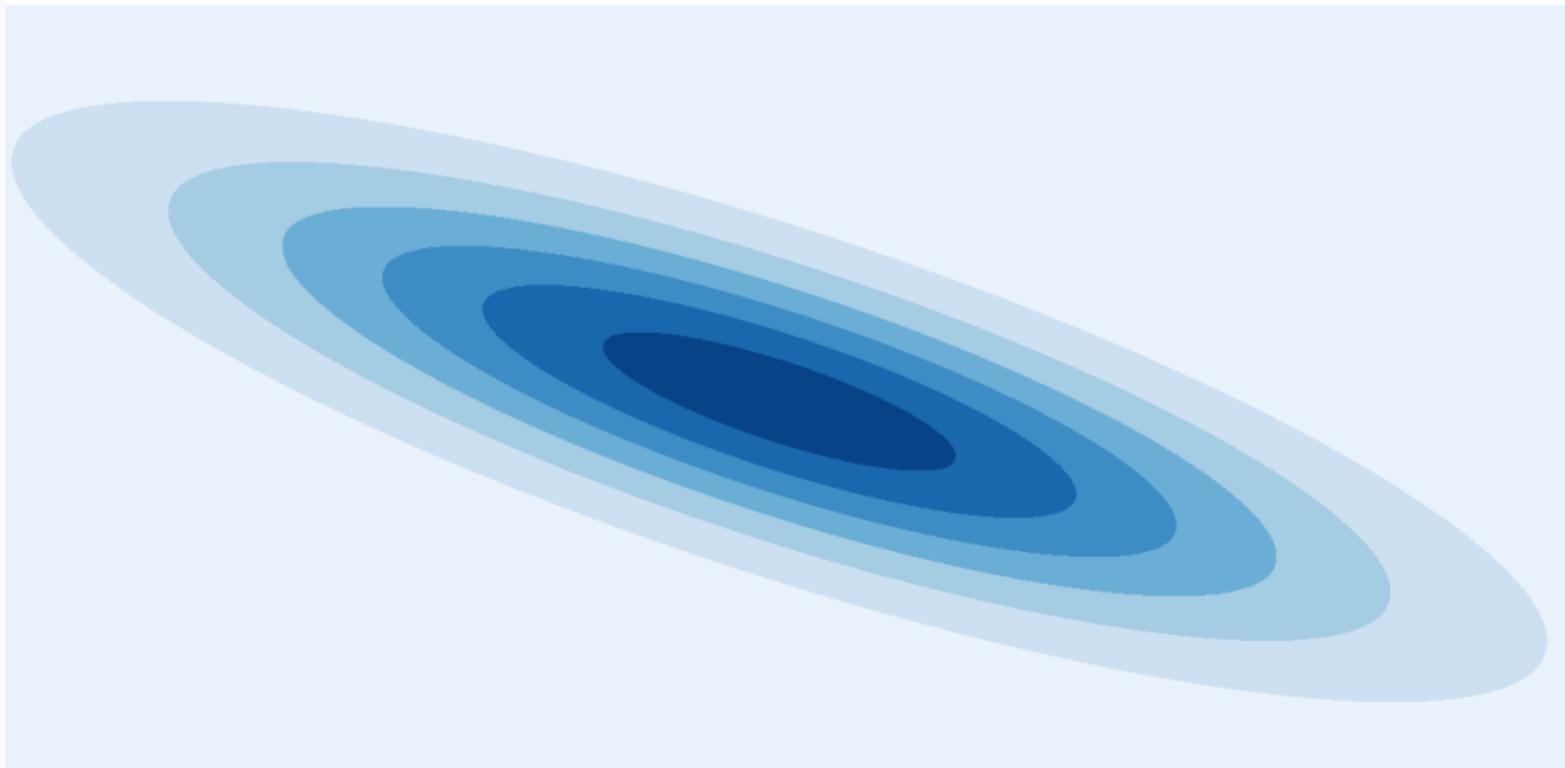
HR image U_{HR}



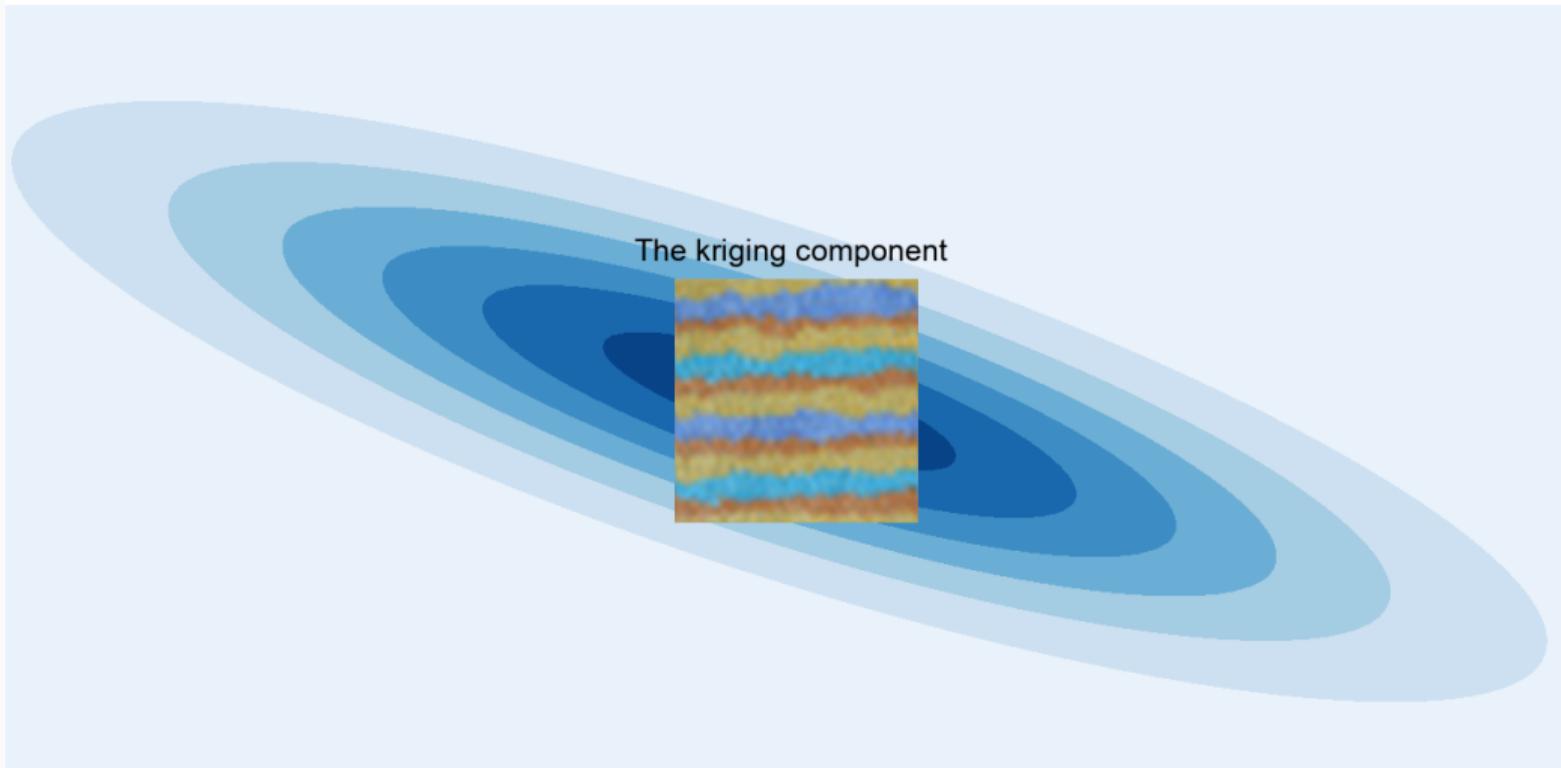
Gaussian SR



Gaussian SR

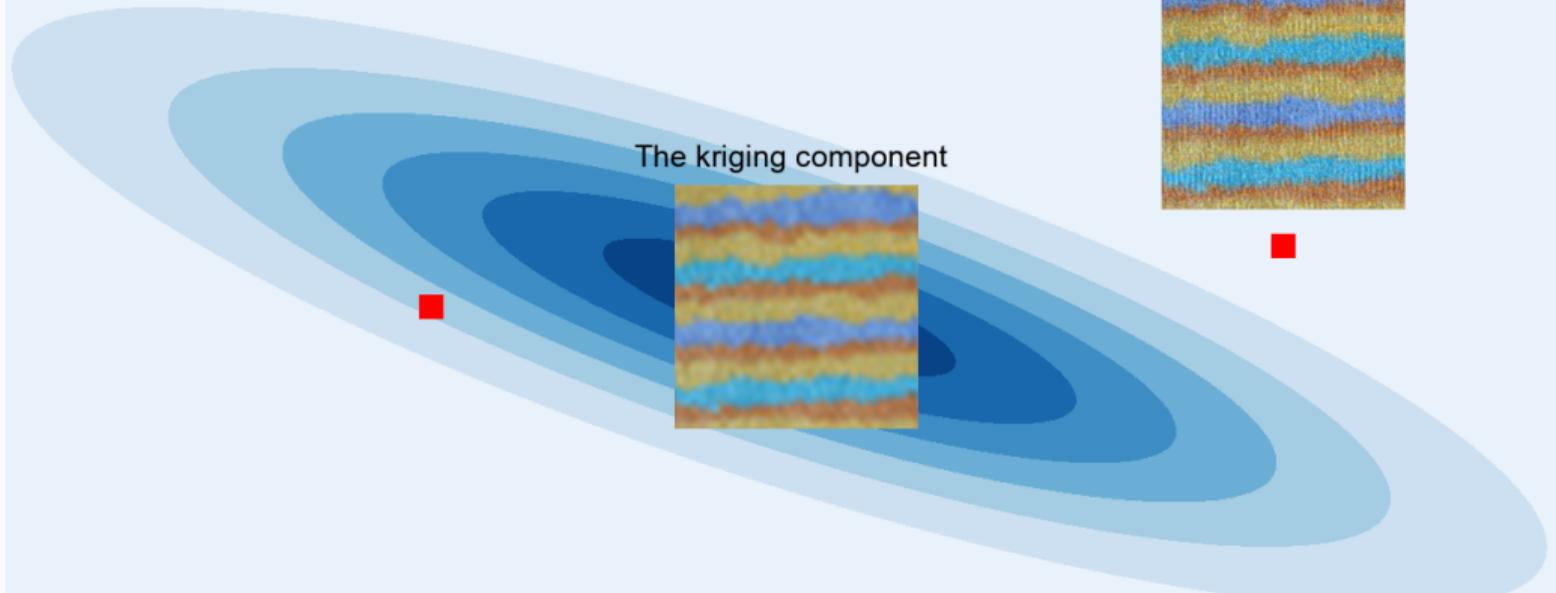
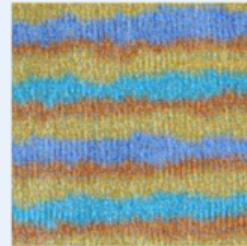


Gaussian SR



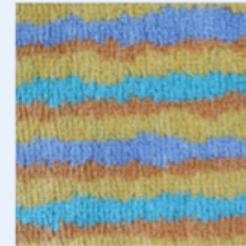
Gaussian SR

Sample 1 = kriging + innovation

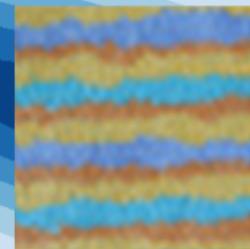


Gaussian SR

Sample 2 = kriging + innovation

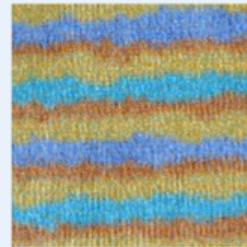


The kriging component

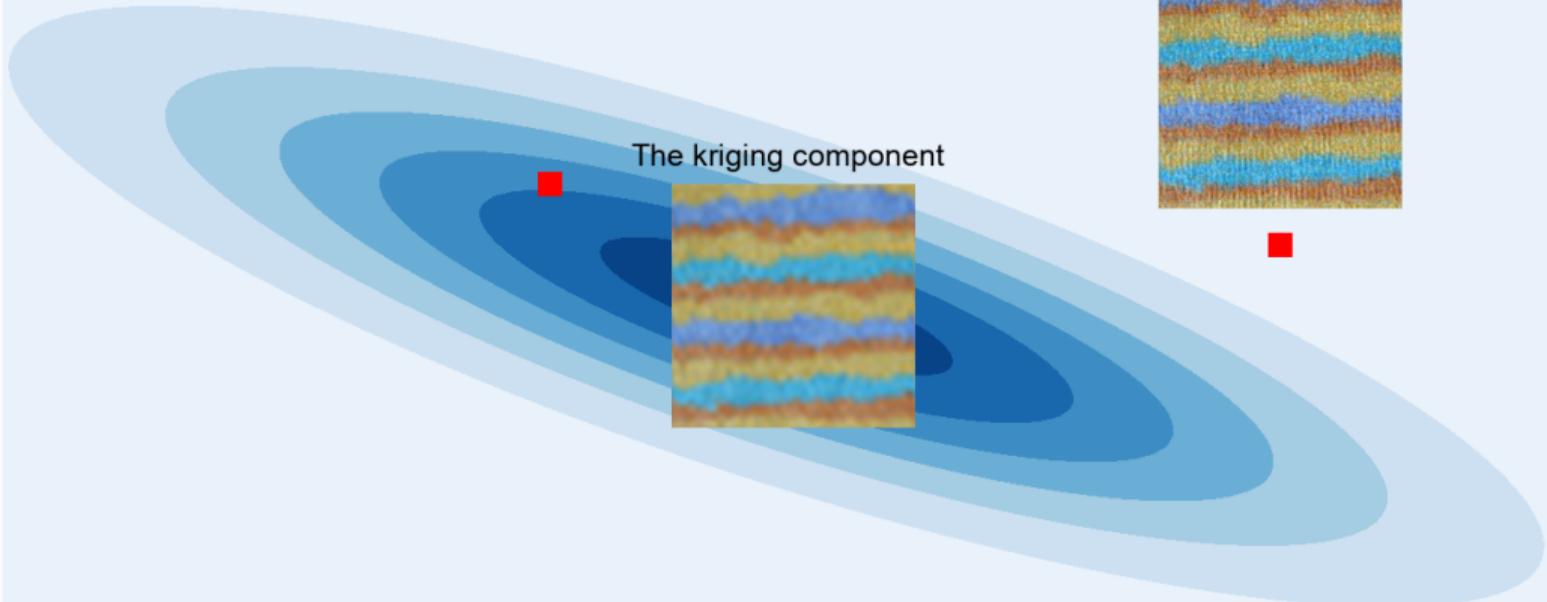
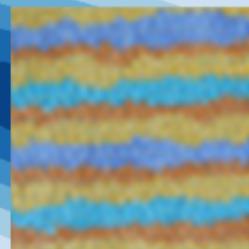


Gaussian SR

Sample 3 = kriging + innovation



The kriging component

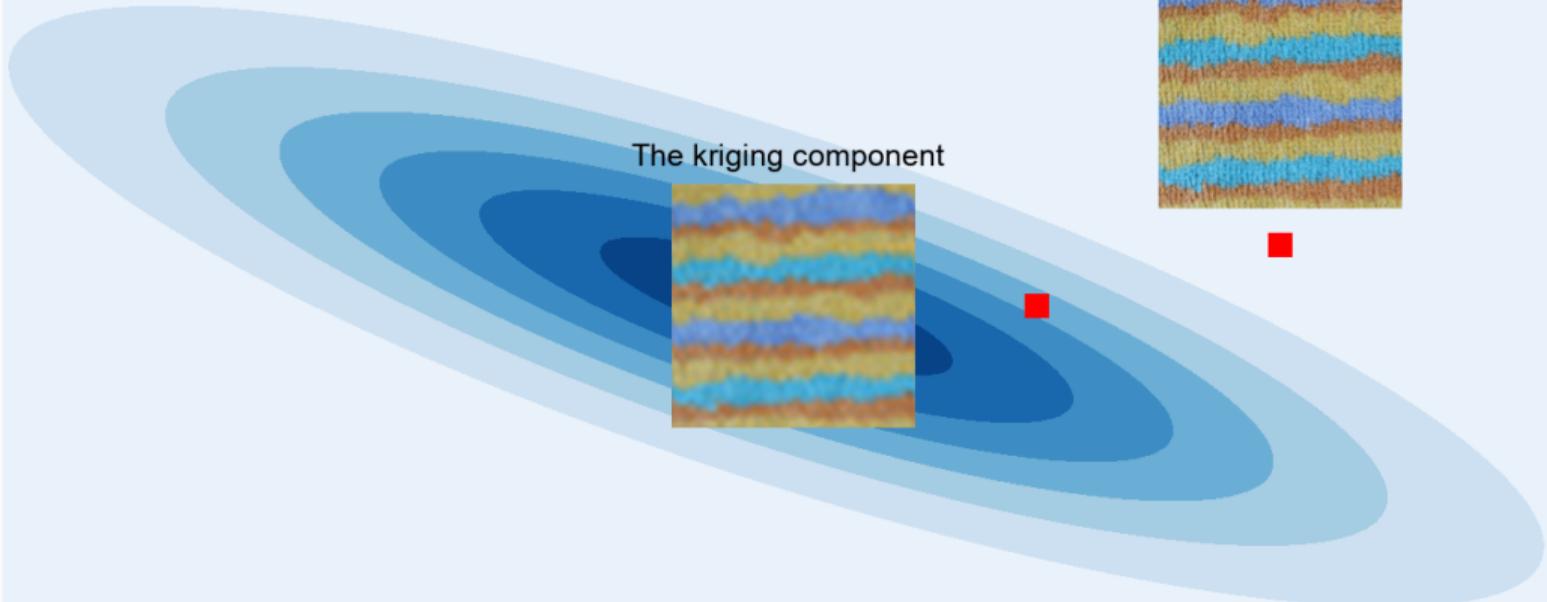
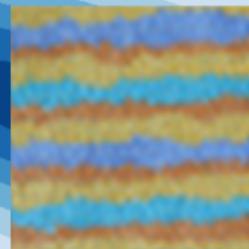


Gaussian SR

Sample 4 = kriging + innovation

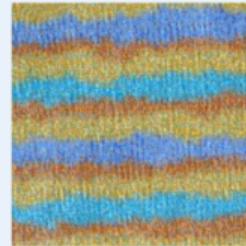


The kriging component

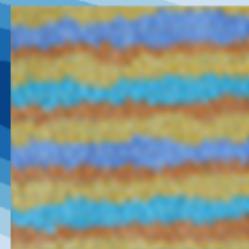


Gaussian SR

Sample 5 = kriging + innovation

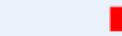
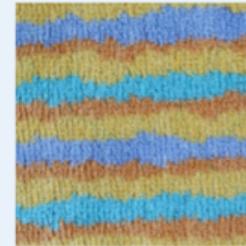


The kriging component

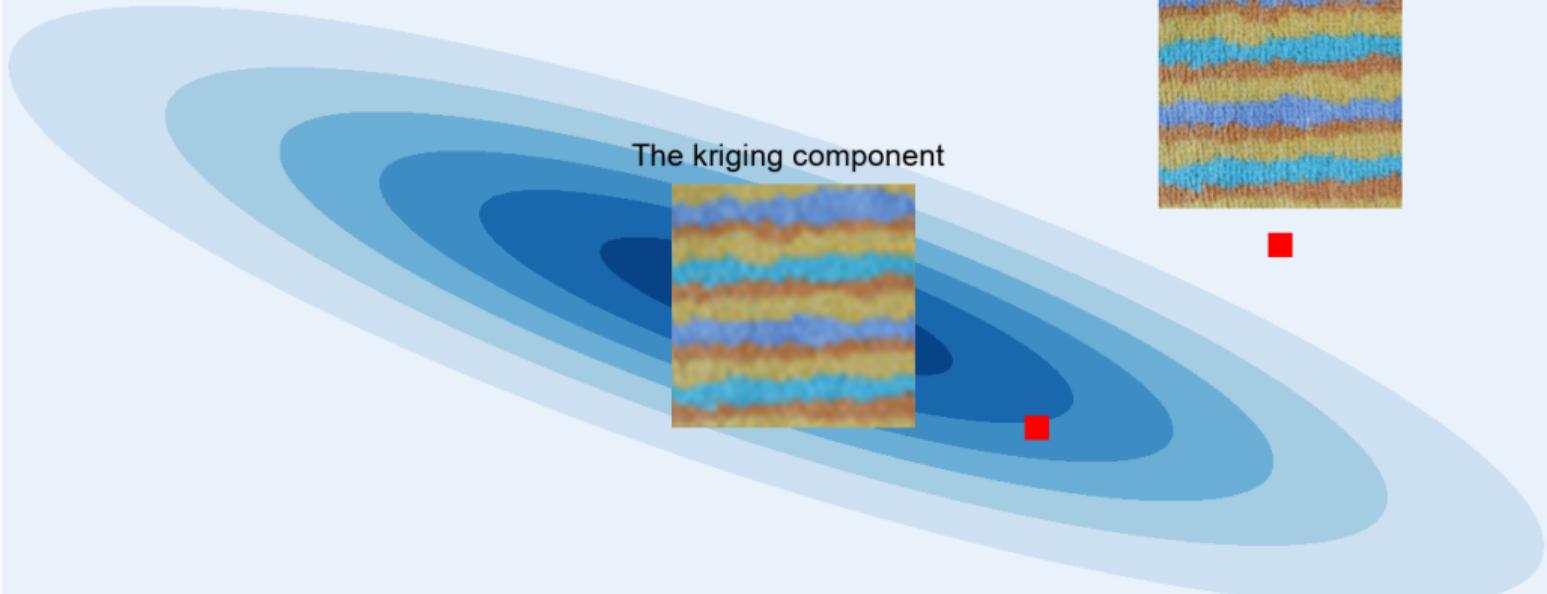
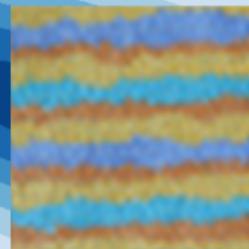


Gaussian SR

Sample 6 = kriging + innovation



The kriging component



Solving the kriging equation

$$\mathbf{A}\boldsymbol{\Gamma}\mathbf{A}^T\boldsymbol{\Lambda} = \mathbf{A}\boldsymbol{\Gamma}. \quad (1)$$

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Solution 1 : $\mathbf{A}\boldsymbol{\Gamma}\mathbf{A}^T$ is a convolution matrix. For each column $\boldsymbol{\lambda}(\mathbf{x})$ of $\boldsymbol{\Lambda}$, the equation becomes:

$$\kappa \star \boldsymbol{\lambda}(\mathbf{x}) = \mathbf{A}\boldsymbol{\Gamma}_{\mathbb{R}^{n \times n} \times \{\mathbf{x}\}}$$

ie

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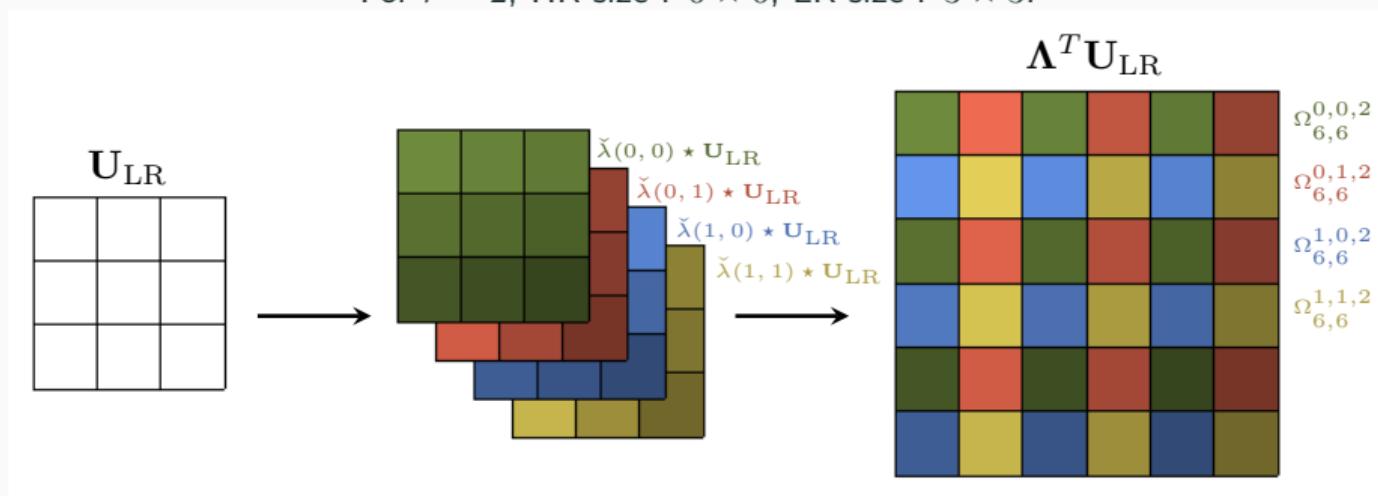
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Solution 2 : There exists a matrix $\boldsymbol{\Lambda}$ such that it has a convolutional behavior. Only r^2 columns of $\boldsymbol{\Lambda}$ are necessary. To store this solution $\boldsymbol{\Lambda}$, only a HR size is necessary.

Application of Λ

For $r = 2$, HR size : 6×6 , LR size : 3×3 .

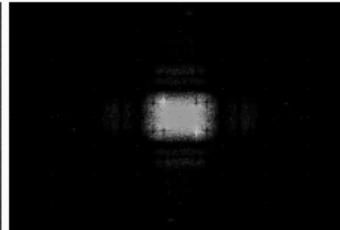


λ convolution

HR image



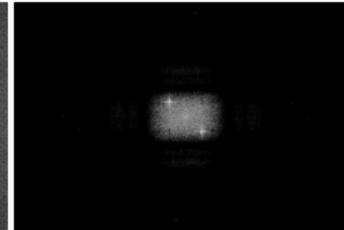
λ



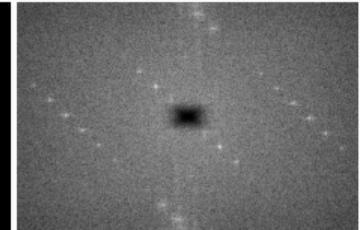
Sample



Kriging comp.



Innovation comp.



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Γ is extracted from \mathbf{U}_{HR}

Solution : Use a reference image with the same law.

With reference image



Reference image

HR image

Samples

Image extracted from [Galerne et al., 2011a]¹⁵

¹⁵Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1. https://doi.org/10.5201/ipol.2011.ggrm_rpn

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With reference image



Reference image

HR image

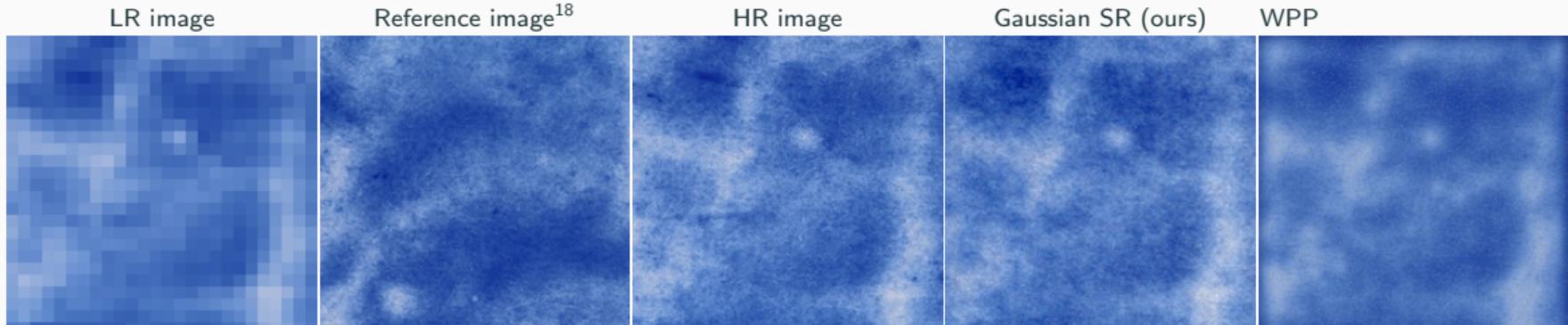
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Image extracted from [Galerne et al., 2011a]¹⁷

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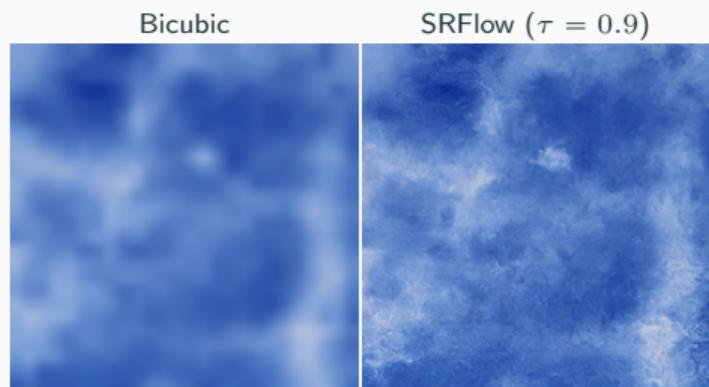
Comparison of Gaussian SR with other methods

Comparison with other methods



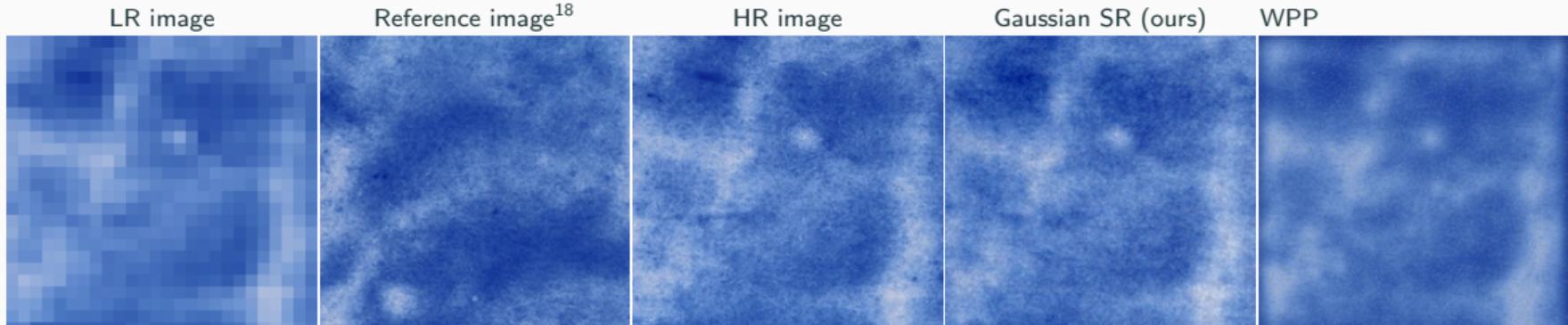
Evaluation metrics

	PSNR (dB) \uparrow	SSIM \uparrow	LPIPS \downarrow	TIME (s)
Bicubic	30.21	0.65	0.54	
Gaussian SR (ours)	26.25 ± 0.05	0.42 ± 0.00	0.12 ± 0.01	0.01 (CPU)
WPP	24.70	0.39	0.22	64.0 (GPU)
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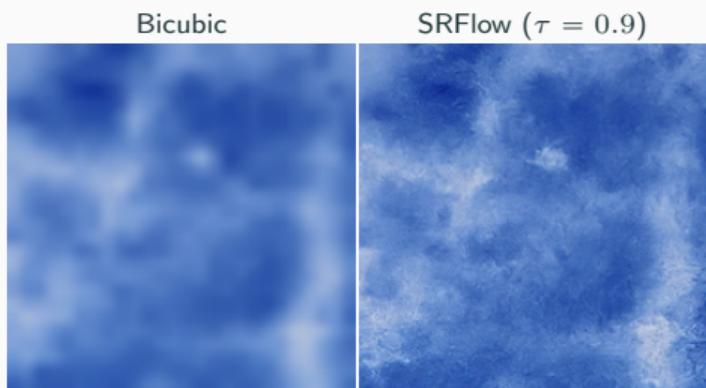
¹⁸Images are extracted from Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1.

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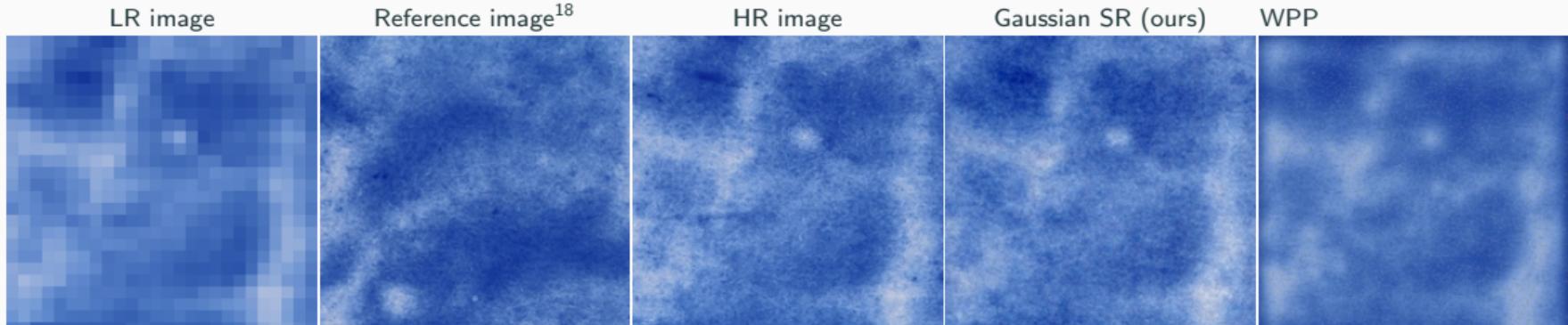
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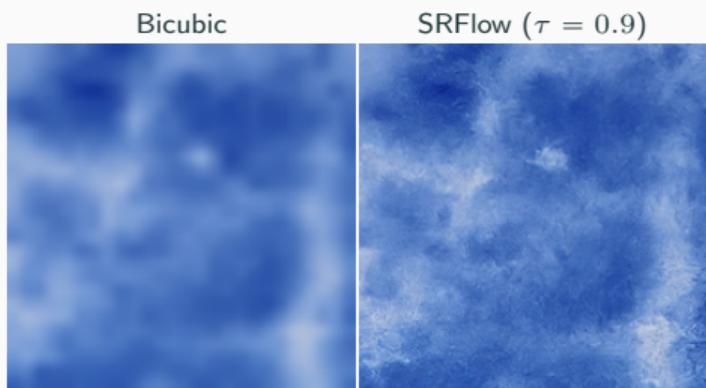
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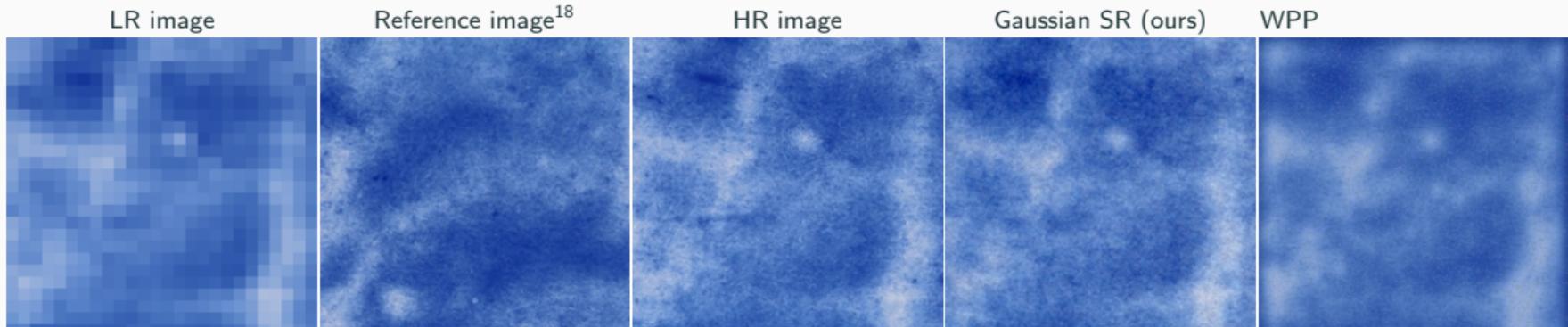
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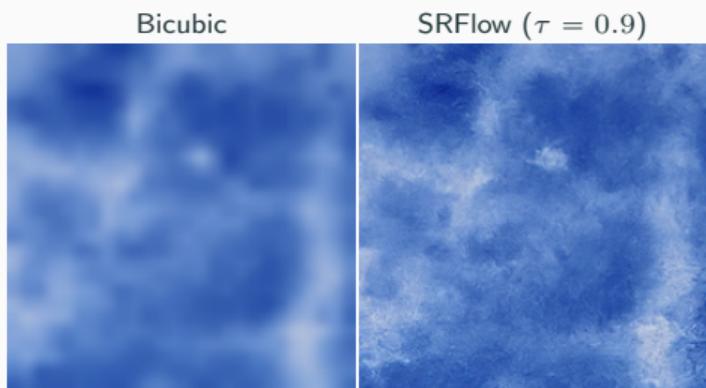
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Comparison with other methods



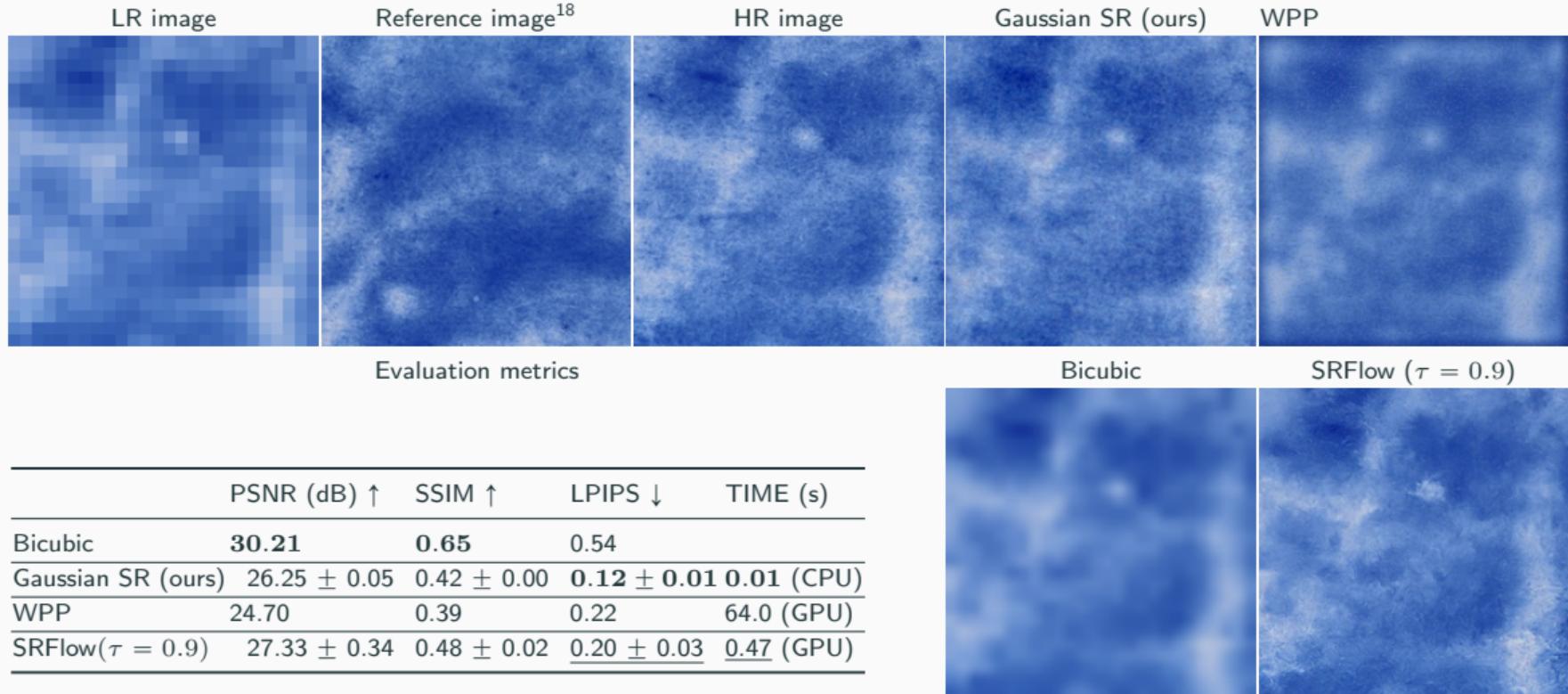
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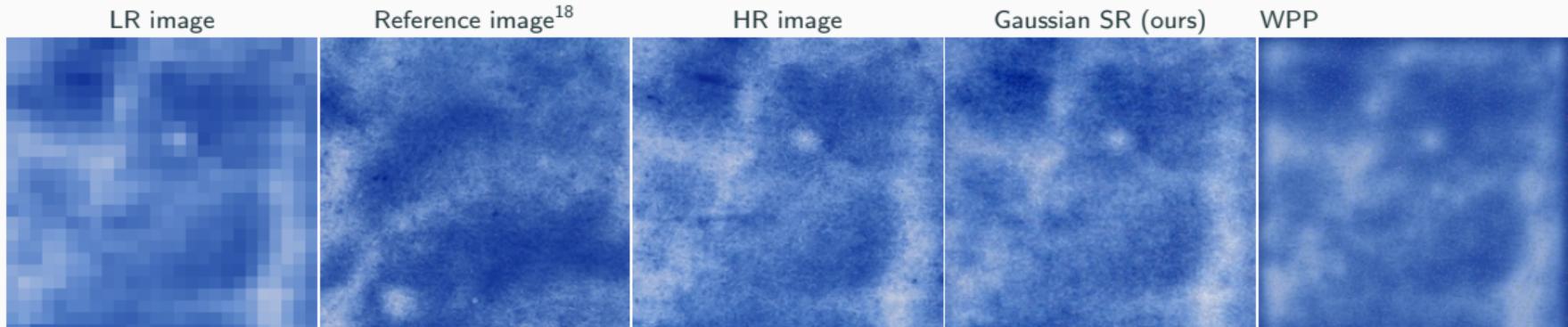
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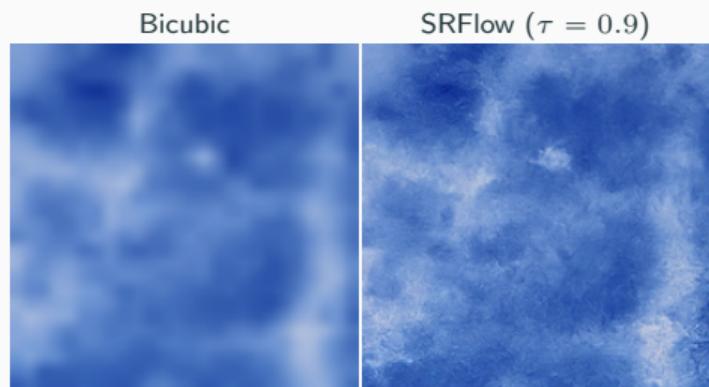
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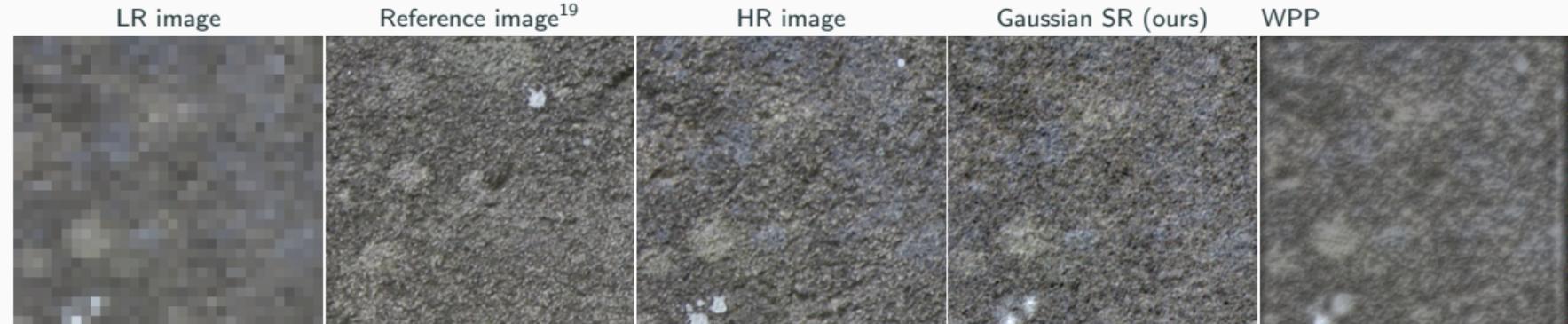
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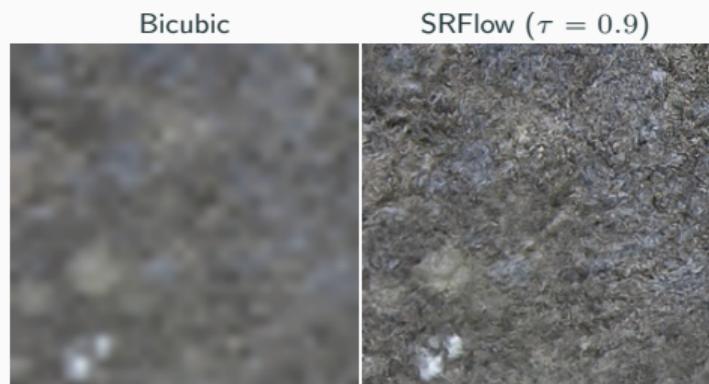
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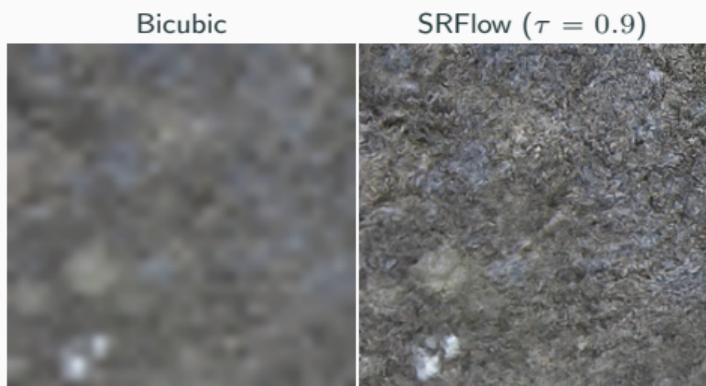
¹⁹Images are extracted from Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1.

Comparison with other methods



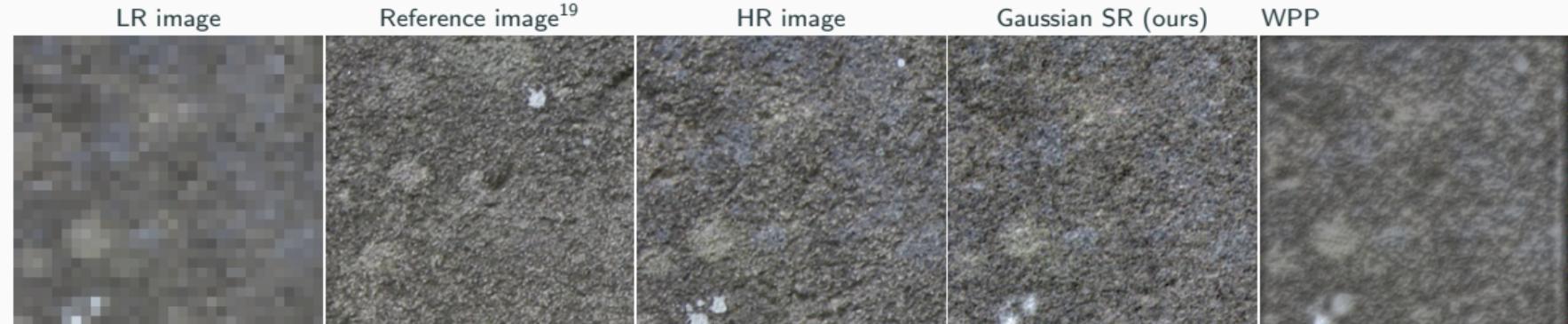
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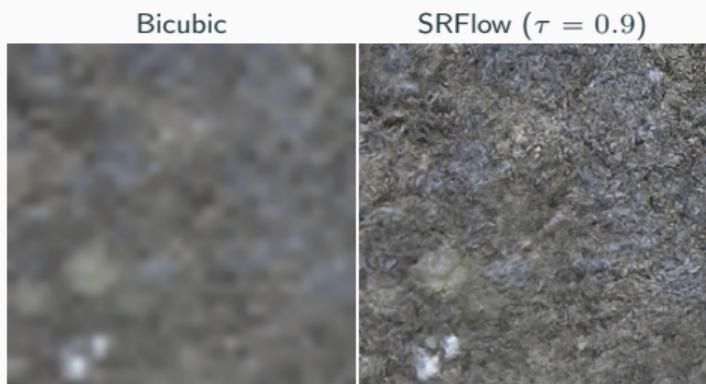
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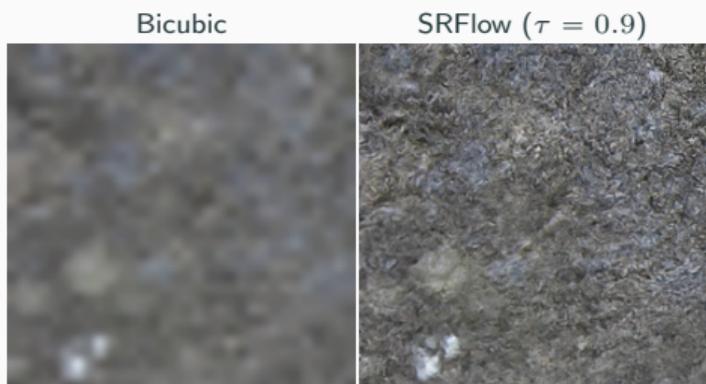
¹⁹Images are extracted from Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1.

Comparison with other methods



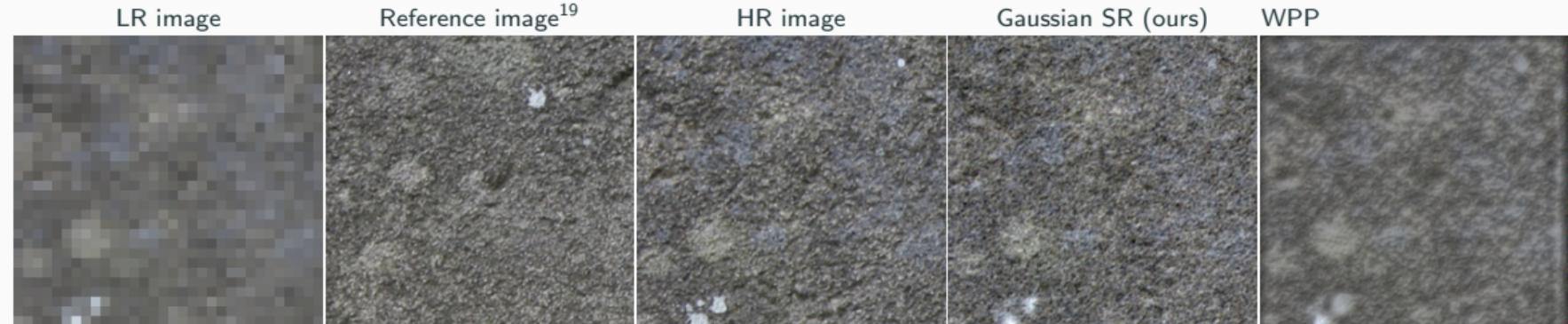
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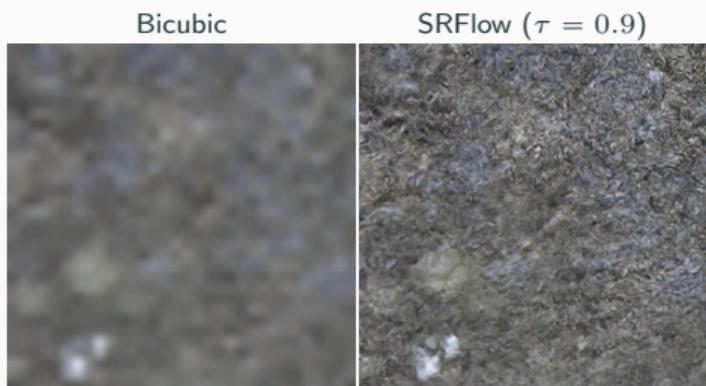
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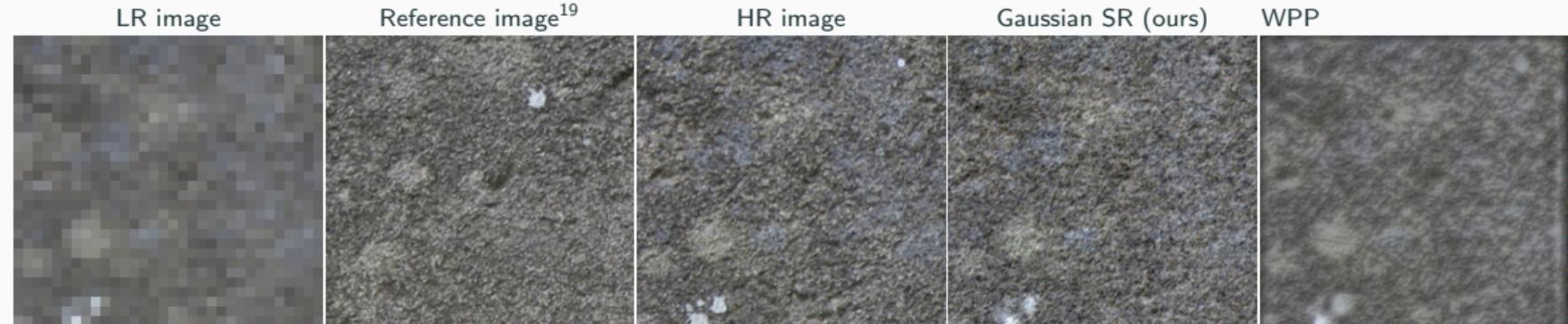
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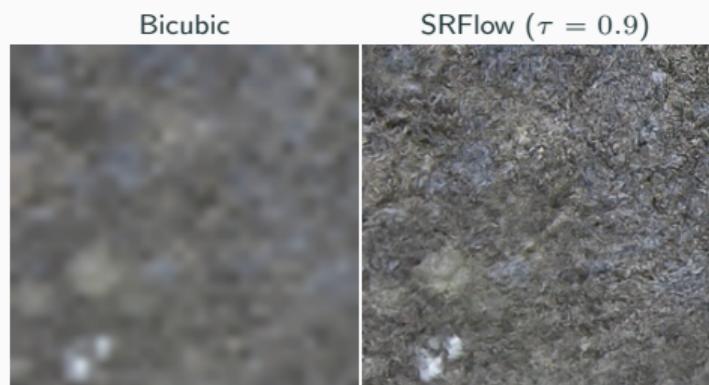
¹⁹Images are extracted from Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1.

Comparison with other methods



Evaluation metrics

	PSNR (dB) ↑	SSIM ↑	LPIPS ↓	TIME (s)
Bicubic	23.52	0.45	0.70	
Gaussian SR (ours)	18.99 ± 0.05	0.14 ± 0.01	0.25 ± 0.01	0.02 (CPU)
WPP	21.12	0.21	0.42	77.0 (GPU)
SRFlow($\tau = 0.9$)	18.99 ± 0.38	0.14 ± 0.01	0.39 ± 0.04	<u>0.55 (GPU)</u>



¹⁹Images are extracted from Galerne, B., Gousseau, Y., & Morel, J.-M. (2011a). Micro-texture synthesis by phase randomization. *Image Processing On Line*, 1.

Proposition 1: Kriging component and MSE

Let $\mathbf{U}_{\text{HR}} \in \mathbb{R}^{\Omega_{M,N}}$ be a HR image, $\mathbf{U}_{\text{LR}} = \mathbf{A}\mathbf{U}_{\text{HR}}$ its LR version, $\boldsymbol{\Lambda} \in \mathbb{R}^{\Omega_{M/r,N/r} \times \Omega_{M,N}}$ be the kriging operator and \mathbf{X}_{SR} the random image following the distribution of the SR samples then

$$\begin{aligned}\mathbb{E}_{\mathbf{X}_{\text{SR}}} (\|\mathbf{U}_{\text{HR}} - \mathbf{X}_{\text{SR}}\|_2^2) &= \|\mathbf{U}_{\text{HR}} - \boldsymbol{\Lambda}^T \mathbf{U}_{\text{LR}}\|_2^2 + \text{Tr} [(\mathbf{I}_{\Omega_{M,N}} - \boldsymbol{\Lambda}^T \mathbf{A}) \boldsymbol{\Gamma} (\mathbf{I}_{\Omega_{M,N}} - \boldsymbol{\Lambda}^T \mathbf{A})^T] \\ &\geq \|\mathbf{U}_{\text{HR}} - \boldsymbol{\Lambda}^T \mathbf{U}_{\text{LR}}\|_2^2.\end{aligned}\tag{2}$$

Simply put, the expected mean square error between the optimal HR image and Gaussian SR samples is always higher than the MSE between \mathbf{U}_{HR} and the associated kriging component $\boldsymbol{\Lambda}^T \mathbf{U}_{\text{LR}}$.

Fails of the method

Reference choice

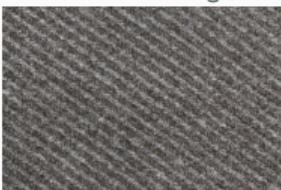
LR image



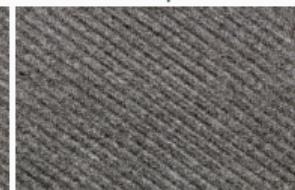
HR image



Reference image



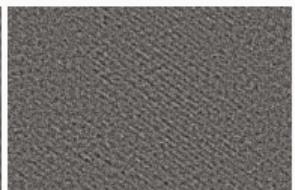
Sample



Kriging



Innovation



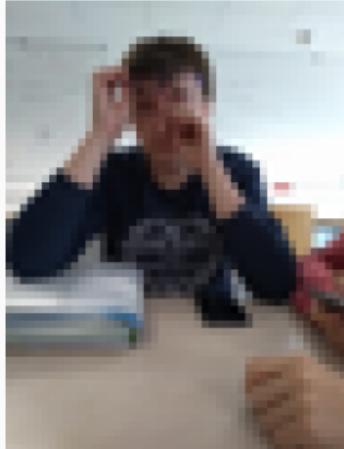
Structured textures



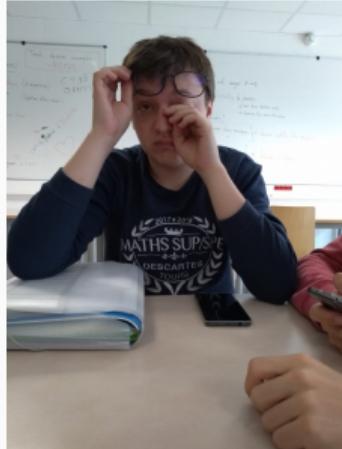
→ Not stationary textures

Structured textures

LR image
 \mathbf{U}_{LR}



HR image
 \mathbf{U}_{HR}



SR Gaussian sample
 \mathbf{U}_{SR}



Kriging comp.
 $\Lambda^T \mathbf{U}_{\text{LR}}$



Innovation comp.
 $\tilde{\mathbf{U}} - \Lambda^T \mathbf{A} \tilde{\mathbf{U}}$



Instability case

HR image
 \mathbf{U}_{HR}



Kriging comp.
 $\Lambda^T \mathbf{U}_{\text{LR}}$



Variance

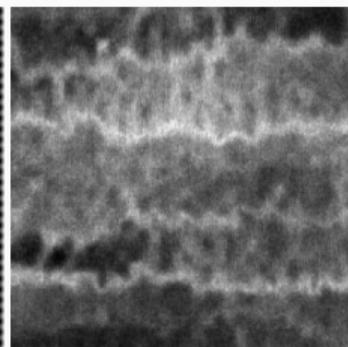
HR image



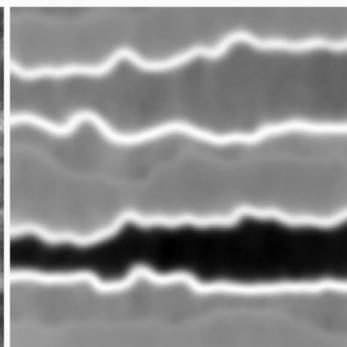
Gaussian SR



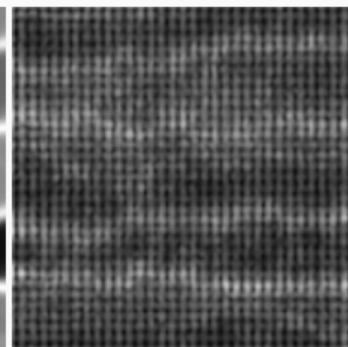
SRFlow



DPS



DDRM



A little lie

The RGB convolution

An grayscale convolution acts like this:

$$\Gamma U = t \star U \quad (3)$$

In Fourier,

$$\widehat{\Gamma U} = \widehat{t} \odot \widehat{U} \quad (4)$$

The RGB convolution

An grayscale convolution acts like this:

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In Fourier,

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An RGB convolution acts like this:

$$(\Gamma \mathbf{U})_i = \mathbf{t}_i \star \check{\mathbf{t}}_1 \star \mathbf{U}_1 + \mathbf{t}_i \star \check{\mathbf{t}}_2 \star \mathbf{U}_2 + \mathbf{t}_i \star \check{\mathbf{t}}_3 \star \mathbf{U}_3, \quad 1 \leq i \leq 3. \quad (5)$$

In Fourier,

$$(\widehat{\Gamma \mathbf{U}})_i = \widehat{\mathbf{t}}_i \odot \overline{\widehat{\mathbf{t}}_1} \odot \widehat{\mathbf{U}}_1 + \widehat{\mathbf{t}}_i \overline{\widehat{\mathbf{t}}_2} \odot \widehat{\mathbf{U}}_2 + \widehat{\mathbf{t}}_i \odot \overline{\widehat{\mathbf{t}}_3} \odot \widehat{\mathbf{U}}_3, \quad 1 \leq i \leq 3. \quad (6)$$

The RGB approximation

$$(\Gamma \mathbf{U})_i = \mathbf{t}_i \star \check{\mathbf{t}}_1 \star \mathbf{U}_1 + \mathbf{t}_i \star \check{\mathbf{t}}_2 \star \mathbf{U}_2 + \mathbf{t}_i \star \check{\mathbf{t}}_3 \star \mathbf{U}_3, \quad 1 \leq i \leq 3. \quad (7)$$

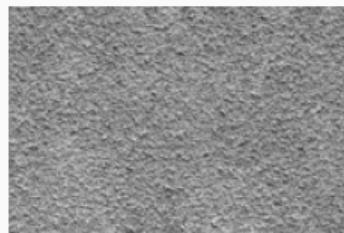
is replaced by

$$\left(\tilde{\Gamma} \mathbf{U} \right)_i = \mathbf{t}_i \star \check{\mathbf{t}}_i \star \mathbf{U}_i, \quad 1 \leq i \leq 3. \quad (8)$$

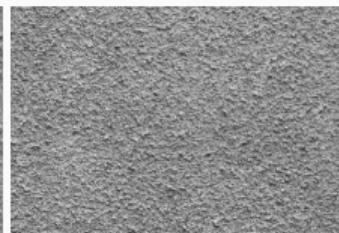
Effect of RGB approximation

Grayscale example

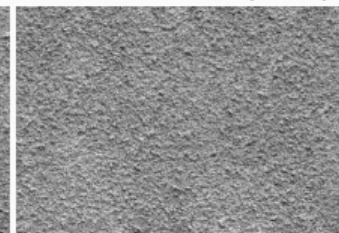
LR image



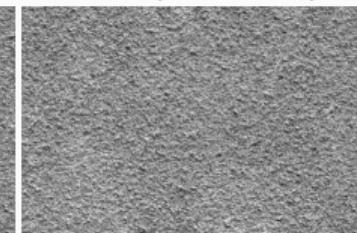
HR image



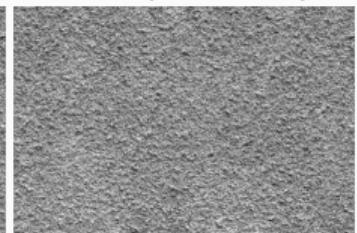
Gaussian SR (ours)



CGD (10^2 steps)



CGD (10^6 steps)



RGB example

LR image



HR image



Gaussian SR (ours)



CGD (10^2 steps)



CGD (10^6 steps)



Effect of RGB approximation

Comparison with the reference CGD algorithm						
	Grayscale image			RGB image		
	Residual (CPU)	Time(s) CGD	PSNR w.r.t (10^6 st.)	Residual (CPU)	Time(s) CGD	PSNR w.r.t (10^6 st.)
Gaussian SR	1.32E-16	0.01	151.17	2.54E-1	0.01	37.94
CGD (10^2 steps)	2.74E-2	0.13	29.16	2.73E0	0.38	25.08
CGD (10^3 steps)	1.03E-3	0.76	47.49	3.78E-1	2.49	30.19
CGD (10^4 steps)	4.72E-5	7.44	67.60	1.36E-1	23.1	35.07
CGD (10^5 steps)	1.30E-8	81.3	145.31	2.37E-2	258	39.71
CGD (10^6 steps)	2.69E-42	749	-	4.97E-3	2588	-

Conclusion

Conclusion

- Our method has a limited scope but has a well-posed mathematical assumption.
- The stationarity assumption is very strong: details are affected in the SR samples.

What you missed :

- The pixel-wise variance can be computed.
- Study of stability.
- Can be used for other ill-posed problems with $\mathbf{A} = \mathbf{SC}$.

Perspectives:

- Application to diffusion models.

Thank you for your attention !

